Control valves RV 702



Kv coefficient calculation

Calculation itself is carried out with respect to conditions of regulating circuit and operating medium according to equations mentioned below. Control valve must be designed to be able to regulate maximal flow quantity at given operating conditions. At the same time it is necessary to check whether minimal flow quantity can be even regulated or not.

Because of eventual minus tolerance 10% of Kv_{...} against Kvs and requirement for possible regulation within range of maximal flow (decrement and increase of flow), producer recommends to select Kvs value higher than maximal operating Kv value:

$$Kvs = 1.2 \div 1.3 Kv$$

It is necessary to take into account to which extent $Q_{\mbox{\tiny max}}$ involve "precautionary additions" that could result in valve oversizing.

Relations of Kv calculation

		Pressure drop	Pressure drop
		$p_2 > p_1/2$ $\Delta p < p_1/2$	$\Delta p \ge p_1/2$ $p_2 \le p_1/2$
	Liquid	Q 100 1	$\frac{\rho_1}{\Delta p}$
Kv=	Gas	$\frac{Q_n}{5141}\sqrt{\frac{\rho_n.T_1}{\Delta p.p_2}}$	$\frac{2.Q_n}{5141.p_1}\sqrt{p_n.T_1}$
KV –	Superh. steam	$\frac{Q_m}{100}\sqrt{\frac{v_2}{\Delta p}}$	$\frac{Q_m}{100}\sqrt{\frac{2V}{p_1}}$
	Sat. steam	$\frac{Q_{m}}{100}\sqrt{\frac{v_{2}.x}{\Delta p}}$	$\frac{Q_m}{100}\sqrt{\frac{2v.x}{p_1}}$

Above critical flow of vapours and gases

When pressure ratio is above critical ($p_2/p_1 < 0.54$), speed of flow reaches acoustic velocity at the narrowest section. This event can cause higher level of noisiness and then it is convenient to use a throttling system ensuring low noisiness (multi-step pressure reduction, damping orifice plate at outlet).

Cavitation

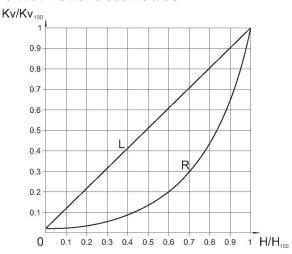
Cavitation is a phenomenon when there are steam bubbles creating and vanishing in shocks - generally at the narrowest section of flowing due to local pressure drop. This event

expressively cuts down service life of inner parts and can result in creation of unpleasant vibrations and noisiness. In control valves it can happen on condition that

$$(p_1 - p_2) \ge 0.6 (p_1 - p_3)$$

Valve differential pressure should be set the way so that neither any undesired pressure drop causing cavitation can occur, nor liquid-steam(wet steam) mixture can create. Otherwise it must be taken into account when calculating Kv value. If the creation of cavitation still threatens, it is necessary to use a multi-step pressure reduction.

Valve flow characteristics



L - linear characteristic

 $Kv/Kv_{100} = 0.0183 + 0.9817 \cdot (H/H_{100})$

R - equal-percentage characteristic (4-percentage) $Kv/Kv_{\text{too}} = 0.0183 \cdot E^{\text{(4.14H1}_{100)}}$

Rangeability

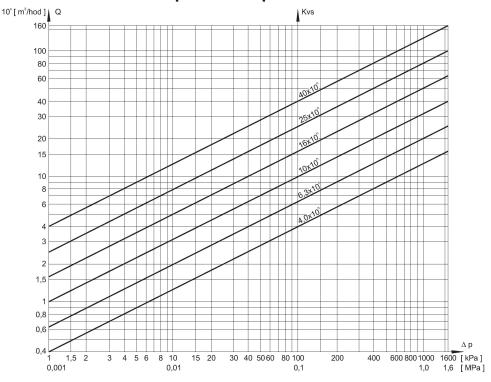
Rangeability is the ratio of the biggest value of flow coefficient to the smallest value. In fact it is the ratio (under the same conditions) of highest regulated flow rate value to its lowest value.

The lowest or minimal regulated flow rate is always higher than 0.

Dimensions and units

Marking	Unit	Name of dimension
Kv	m³/hour	Flow coefficient under conditions of units of flow
Kv ₁₀₀	m³/hour	Flow coefficient at nominal stroke
Kvs	m³/hour	Valve nominal flow coefficient
Q	m³/hour	Flow rate in operating conditions (T ₁ , p ₁)
Q _n	Nm³/hour	Flow rate in normal conditions (0 °C, 0.101 MPa)
Q _m	kg/hour	Flow rate in operating conditions (T ₁ , p ₁)
p,	MPa	Upstream absolute pressure
p ₂	MPa	Downstream absolute pressure
p _s	MPa	Absolute pressure of saturated steam at given temperature (T ₁)
Δρ	MPa	Valve differential pressure ($\Delta p = p_1 - p_2$)
$\overline{\rho_1}$	kg/m³	Process medium density in operating conditions (T ₁ , p ₁)
ρ_n	kg/Nm³	Gas density in normal conditions (0 °C, 0.101 MPa)
V_2	m³/kg	Specific volume of steam when temperature T ₁ and pressure p ₂
V	m³/kg	Specific volume of steam when temperature T _i and pressure p _i /2
T ₁	K	Absolute temperature at valve inlet (T ₁ = 273 + t ₁)
x	1	Proportionate weight volume of saturated steam in wet steam

Diagram for the valve Kvs value specification according to the required flow rate of water Q and the valve differential pressure Δp



The diagram serves to specify the valve Kvs value regarding to the required flow rate of water at a given differential pressure. It can be also used for finding out the differential pressure value of the existing valve in behaviour with the flow rate. The diagram apllies to water with the density of 1000 kg/m³.

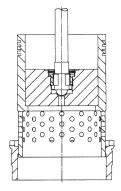
For the value Q = q .10°, it is necessary to calculate with Kvs = k .10°. Example: water flow rate of 16 .10° = 1,6 m³/hour corresponds to Kv = 2,5 = 25. 10 when differential pressure 40kPa.

Application of multi-step pressure reduction

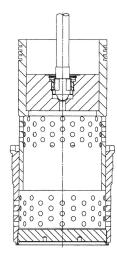
When the valves are designed for operation in above-critical differential pressure (p, /p, <0,54 when throttling steam and gases), or when diff. pressure value is higher than the recom-

mended service diff. pressure, it is effectual to use a throttling system in two or three steps to prevent the cavitation from creating and to ensure both a long service life of the valve inner parts and low noisiness when operating.

One-step pressure reduction



Two-step pressure reduction



Application of orifice plate

In case of above-critical flow, the producer recommends to instal one or more orifice plate at the valve outlet to stream-line the process medium flow and to lower the noisiness. The concrete valve execution (No. of orifice plates) is designed according to pressure ratio and it is recommended to consult it with the producer.



Control valves Inlet DN 25, 50, 100, 125, 150, 250 Outlet DN 25 to 600 PN 16 to 400

Description

The valves with extended outlet series RV 702 are singleseated control valves of a unit construction designed to fit in all demands of an appliance the valve is designed for. The pressure-balanced, multi-step throttling system is always designed to eliminate the valve's high differential pressures with a high resistance to wearing caused by flow and effects of expanding steam. It also ensures a low noisiness level. The valve is equipped with packing "Live Loading".

The valves are delivered with weld ends.

The valves are actuated with linear actuators. The connection is designed for using both domestic and foreign actuators of the following producers: ZPA Nová Paka, ZPA Pečky, Regada Prešov, Auma, Schiebel, EMG-Drehmo, Foxboro.

Process media

The valves are especially designed to control the flow and pressure of vapours and gases without impurities. The producer recommends to pipe a strainer into pipeline in front of the valve when impurities are present. Impurities can affect the quality and reliability of regulation and can cause a reduction of the valve service life. The common process media are for example saturated or superheated steam and other media with no special demands on the used type of material of the valve. The valve application for any other media must be consulted with the producer because of the type of material that is in contact with the process medium.

Application

The sphere of application of these valves continues in the sphere for the valves series RV 502. They are especially designed for industry applications such as heating plants, power plants or regulation of technological processes. The max. permissible operating pressure values correspond to EN 12 516-1, see page 23 of this catalogue.

Installation

The valves must be piped the way so that the process medium flow will coincide with the arrows indicated on the valve body. They can be installed in horizontal, vertical or inclined pipeline in any position except the position when the actuator is under the valve body. The valves DN 250 can be piped in horizontal pipeline only. The actuator cannot be tilted.

Recommended differential pressures

In regard to the pressure balancing of the plug and to linear forces of usable actuators, the valves' application in high differential pressures is not limited by the forces caused by process medium pressure but by the type of used throttling system. A recommended max. differential pressure for one step of multi-step pressure reduction is 5.0 MPa when perforated plug and perforated cage are used. It is recommended to consult the concrete cases with the producer with regard to pressure ratio and parametres of other equipment.

Technical data

Series	RV 702						
Execution	Control valve, single-seated, straight-through, with pressure-balanced plug,						
	with extended of	outlet and orifice plate in ex	tended outlet				
Range of nominal size	Inlet [ON 25 to 250; outlet DN 25	to 600				
Nominal pressure	Inlet PN 160 to 320, outlet PN 16 to 250	Inlet PN 160 to 400	outlet PN 16 to 320				
Body material (including weld ends)	Cast steel 1.0619 (GP 240 GH)	Alloy steel 1.7357 (G17CrMo5-5)	Stainless steel 1.4931 (GX23CrMoV12-1)				
Material of weld ends	1.0425 (P 265 GH)	1.7335 (13CrMo4-5)	1.4922 (X20CrMoV 11-1) 1.4923 (X22CrMoV 12-1) 1.4903 (X10CrMoVNb 9-1)				
Seat material: DN 25, 50, 100, 125, 150, 250	17 021.6 (1.4006)	17 021.6 (1.4006); 42 2906.5 (1.4027) + stellited seat STELIT 6					
Plug material: DN 25, 50, 100, 125, 150, 250	17 348.4	4 (1.4571) + stellited seat \$	STELIT 6				
Operating temp. range	-20 to 400°C	-20 to 550°C	-20 to 600°C				
Weld ends	A	.cc. to ČSN 13 1075 (3/199	1)				
Trim	One	or two-step pressure redu	ction				
	Perfora	ated plug - seat (cage), orifi	ce plate				
Flow characteristic	Linear, equal-percentage						
Leakage rate	Acc. to ČSN EN 1349 (5/2001) Class III, execution with higher tightness Class V						
Packing	Graphite - Live Loading						

Range of Kvs values

DN	25/XXX	50/XXX	100/XXX	125/XXX	150/XXX	250/XXX			
Multi-step pressure reduction		Kvs v	ear flow characte	eristic					
1	1.6 - 8.0	3.2 - 32	10 - 125	16 - 360 *)	16 - 360 *)	40 - 630			
2	1.25 - 8.0	2.5 - 32	8.0 - 100	12.5 - 250	12.5 - 250	40 - 500			
Multi-step pressure reduction		Kvs values [m³/h] - equal-pe	rcentage flow ch	aracteristic				
1	2.5 - 6.3	6.3 - 25		32 - 125	50 - 320				
2	1.6 - 4.0	5.0 - 20	12.5 - 50	25 - 80	25 - 80	25 - 80 50 - 160			

^{*)} For PN 160 and 250 only, for PN 320 and 400 Kvs_{max} = 250 m³/h

Nominal values of Kvs are understood as multiplies of 10 of the progression of selected number R10 (1.0; 1.25; 1.6; 2.0; 2.5; 3.2; 4.0; 5.0; 6.3; 8.0; 10.0). They are specified individually for

every valve acc. to the customer's requirements and value within the appropriate range showen in the table above. Parameteres of outlet (DN, PN) can be modified on request.

Dimensions and weights of RV 702 with weld ends *)

DN	V ₁	V_2	V ₃	L	Н	m	m _{max}
	[mm]	[mm]	[mm] [mm]		[mm]	[kg]	[kg]
25/40	100	260	160		16		
50/100	110	320	160		25		
100/200	170	405	160	880	40		
125/250	225	466	160		63		
150/200	225	466	160		63		
150/300	225	466	160	1015	63		
250/500	345	675	210		100		

^{*)} There are only recommended combination of DN for inlet and outlet of RV 702 valve.

Note: Mentioned weights are approximate. The missing data are to be specified by the producer.

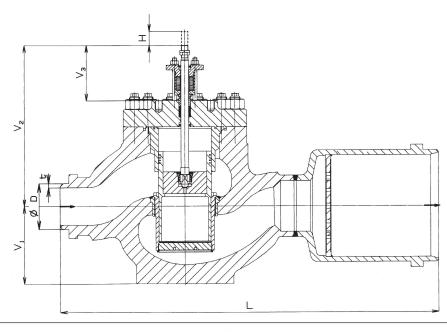
Connecting dimensions of weld ends

				Р	N			
	16 - 40	63	100	160	250	320**	400**	16-400
DN	t	t	t	t	t	t	t	D
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]
25	2.6	2.6	2.9	4	5	6	7.1	33.7
40	2.6	2.9	3.6	5	7	6.8	11	48.3
50	2.9	3.2	4.5	6.3	8	10	14.2	60.3
65	3.2	3.6	5	7	10	13	17.5	76.1
80	3.6	4	5.6	8	12.5	14.2	19	88.9
100	4	5	7	10	14	16	20	114.3
125	4.5	5.6	8	12.5	18	20	23	139.7
150	5	7	10	14	20	23	26	168.3
200	6.3	8	12.5	18	25	28	32	219,1
250	7	10	16	22	32	35	38	273
300	8	12.5	18	25				323.9
350	9	12.5	20	28				355.6
400	11	14	20	32				406.4
500	14	18	25					503
600*	18	23						610

^{*} For DN 600 - weld ends connection acc. to LDM execution.

These combinations of DN and PN are not available

Control valve RV 702 with weld ends



m - weight of the valve without orifice plates m_{max} - weight of the valve with 3 orifice plates

^{**} For PN 320, 400 - weld ends connection acc. to LDM execution.

Valve complete specification No. for ordering RV 701

	To a second			XXX	XXXX	XX	- (XX/XX)	/ XXX	- (XX/XX)
1. Valve	Control valve	RV							
2. Series	Straight-through valve with extended outlet		702						
Type of actuating	Electric actuator			E					
1) Pneumatic actuators or	Pneumatic actuator			Р					
for DN 150	Electric actuator Modact MTR 2)			EPD					
2) Applycable to max. DN	150 Electric actuator Modact MTN Control 2)			EYA					
rippry cazie to maxi 271	Electric actuator Modact MTN 2)			EYB					
	Electric pohon Modact MOP 52 030			EYE					
	El. actuator Modact MOP Control 52 030			EYF					
	Electric actuator Modact MOP 52 031			EYG					
	El. actuator Modact MOP Control 52 031			EYH					
	Electric actuator Auma SAR 7.5			EAG					
	Electric actuator Auma SAR Ex 7.5			EHH					
	Electric actuator Auma SAR 10.1			EAK					
	Electric actuator Auma SAR Ex 10.1			EAJ					
	Electric actuator Schiebel rAB5			EZG					
	Electric actuator Schiebel exrAB5			EZH					
	Electric actuator Schiebel rAB8			EZK					
	Electric actuator Schiebel exrAB8			EZL					
	Pneumatic actuator Foxboro PO 700 1)			PFG					
	Pneumatic actuator Foxboro PO 1502 1)			PFD					
4. Connection	Weld ends				4				
5. Body material	Cast steel 1.0619 (-20 to 400°C)				1				
-	Stainless steel 1.4931 (-20 to 600°C)				5				
(operating temp. ranges a	Alloy steel 1.7357 (-20 to 550°C)				7				
specified in parentheses)	Other material on request				9				
6. Packing	Graphite - Live Loading				5				
7. Multi-step pressure	One-step pressure reduction				1				
reduction	Two-step pressure reduction				2				
8. Flow characteristic	Linear - Leakage rate class III.					L			
	Linear - Leakage rate class V.					D			
	Equal-percentage - Leakage rate class III					R			
	Equal-percentage - Leakage rate class V.	_				Q			
9. No. of orifice plate	Max. 3					Х			
10. Nominal pressure	PN inlet / outlet					- 10	(XX/XX)		
11. Max. operating temp								XXX	
12. Nominal size	DN - acc. to the valve's execution								(XX/XX

Order example:

Two-way, control valve DN 80, PN 160, with electric actuator Modact MTN Control, body material: cast steel, weld ends, packing Graphite, two-step pressure reduction, linear flow characteristic is specified as follows: **RV 702 EYA 4152 L0 160/400-80.**

Note

PN and DN of outlet, multi-step pressure reduction No. of orifice plate possibly different type of actuating is possible after the agreement with the producer.

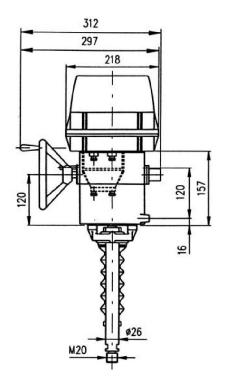


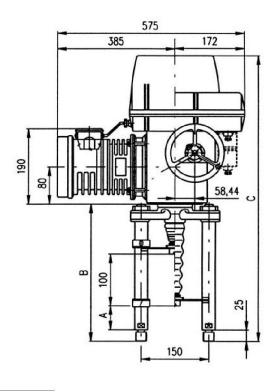
Electric actuator Modact MTR Regada

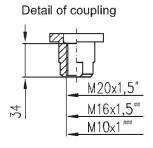
Technical data

Type	Modact MTR
Marking in valve specification No.	EPD
Voltage	230 V
Frequency	50 / 60 Hz
Motor power	16 or 25 W
Control	3 - pos. c. (in connection with NOTREP positioner - continuous)
Nominal force	10, 16, 25 kN
Travel	12,5 to 100 mm
Enclosure	IP 54 (IP 65 on request)
Process medium max. temperature	Acc. to used valve
Ambient temperature range	-25 to 50°C
Ambient humidity limit	90 % (tropical execution 100 % condensation)
Weight	27 to 31 kg

Dimensions of Modact MTR







Columns		in aci hrea		Columns	bolt					
	Α	В	С	Version	Α	В	С			
P-1045a/C	130	378	707	P-1045a/H	130	400	729			

⁴⁾ RV 702, DN 100÷150 ⁴⁴⁾ RV 702, DN 50 ⁴⁴⁰⁾ RV 702, DN 25

Specification of Modact MTR

	Electric actuator MTR, linear 52 420. Mild up to hot dry with temperature range (-25 °C to +50 °C)									X 0	- X	X	Χ	X	X	/ X	X		
Electric conection		crature ra	Voltage Wiring diagram								_	H		+	+	+			
To terminal board											9	Н			-				
To connector				230 V AC	Z296			8	_		\forall		\top	\vdash					
Screw version	Switch	hing-off st 1)2)	Ra	Rated opera- ting speed Speed Po			Powe	Electric mo r Speed	tor Current										
_ 16 000/32-0		16.0 kN		2 mm/min.	38 -	32 mm/min.	16 W		0.31 A			Е			+	+			
25 000/32-0		25.0 kN		32 mm/min 39 32 mm/min							G			+		H			
16 000/50-0		16.0 kN		0 mm/min.		50 mm/min.	25 W	/ 1 250	0.41 A		+	Н		\top	1	1			
Control bo	oard versi	on		Operatir	ng stro	oke	١	Wiring diag	ram										
8				16	mm								В						
				25	mm			Z298				П	С						
Electromechani	cal contro ocal contr			40	mm			2298					Е						
Without it	Juan Conti	UI		63	mm								F						
Tran	Transmitter			Connection	on	Output	Wiring diagram												
Without	transmitte	er					_						Α						
		Single		1x100 Ω		2	Z5a			_	П	П	В	\top	\top				
B. T. C.		Double				2x100 g	2	Z6:	а			П		С		\top	Т		
Resistive		Single		Single				1x2000	Ω	Z5:	а					F		\top	Г
		Double	2x2000 Ω		Ω	Z6a						Р	\top	\top	Т				
2	Without	power sup	ver supply			Z10a				П		S							
	With p	ower supp	pply 2-wire 4 - 20 mA		IA	Z269a						Q							
	Without	nout power supply ith power supply nout power supply ith power supply						0 - 20 m		Z25	7a					Т			
Resistive with	With p			,		0 - 20 m	IA	Z260a						U					
current converter	Without					3-wire		4 - 20 m	. ^	Z257a						V			
	With p			3-WII 6		4 - 20 111	iA	Z26	0a					W					
	Without pow					0 - 5 m/	^	Z25	7a					Υ					
2		ower supp				0 - 5 117	٦.	Z260a						Z					
Capacitive		power sup		2-wire		4 - 20 m		Z10)a					1					
CPT	With p	ower supp	ly	2-11116		4 - 20 111		Z26	9a					J					
Mechanical connection		nnecting nt / stroke		Pillar spaci Bore of flar	ng / nge	Thread stem 3		Dimens draw											
Columns	1	30/100		150/ —	•	M20x1.5 M16x1.5, M		P-1045a/C; F	P-1045a/H						С				
		Addition	nal e	quipment				Wiring di	agram										
Without additi	onal equi	pment; adj	juste	d max. switch	ing-of	f thrust from r	ange			\Box		П	П	\top	\top	0	1		
A 2 additional p								Z29	18					T		0	2		
B Adjustment of	switching	g-off thrust	for r	equired value									П	\top		0	3		

Combinations available and specification codes: A+B = 07

Notes:

1) State the switching-off thrust in your order by words. If not stated it is adjusted to the maximum rate of the corresponding range. The load torgue equals minimally the maximum switching-off thrust of the choosing range multiplied by 1.3.

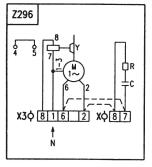
2) The maximum load thrust equals the max. Switching-off thrust multiplied by:

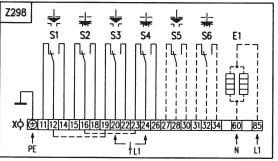
- 0.8 for duty cycle S2-10 min., Or S4-25%, 6 - 90 cycles per hour

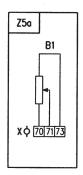
- 0.6 for duty cycle S4-25%, 90 - 1200 cycles per hour

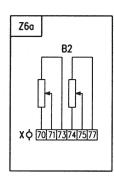
3) The thread in the coupling is to be specified in the order by words.

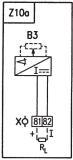
Wiring diagram of actuator Modact MTR

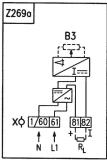


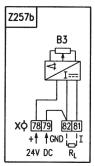


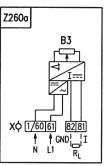












Notes:

- For the EA version with connection to the terminal board, the terminal 1/60 (the wiring diagrams Z269a and Z260a) is leaded out to the terminal No. 1.
- 2. For EA version with connection to the terminal board the actuator is not equipped by the jumper X3:6-X:7 and X3:2-X:8 (Z296) from manufacturing plant (it is necessary to connect it by customer).

Legend:

Z5a connection of single resistive transmitter connection of double resistive transmitter

Z10a connection of resistive with current converter of capacitive transmitter - 2-wire without supply

Z257b connection of resistive transmitter with current converter - 3-wire

Z260a connection of resistive transmitter with current converter - 3-wire with power supply

Z269a connection of resistive transmitter with current converter or capacitive transmitter - 3-wire with power supply

Z296 conection of 1-phase electric motor

Z298 conection of thrust and position switches and space heater

B1 resistive trasmitter (potentiometer) single B2 resistive trasmitter (potentiometer) double

B3 capacitive transmitter
S1 thrust switch "open"
S2 thrust switch "closing"
S3 position switch "open"
S4 position switch "closed"
S5 additional position swich

S5 additional position swich "open"S6 additional position "closed"

M motor
C capacitor
Y motor's brake
E1 space heater
X terminal board

X3 electric motor's terminal board

I/U input (output) current (voltage) signals

R reducting resistor R_L loading resistor





Electric actuators Modact MTN and Modact MTN Control ZPA Pečky

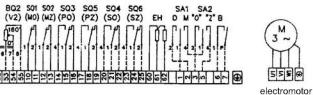
Technical data

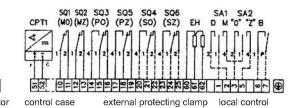
EYA 3 x 220 V / 400 V	EYB				
3 x 220 V / 400 V	/ /0				
	(3 x 220 V/380V)				
50	Hz				
See specifi	ication table				
3 - position control or continuou					
15000 and 25000 N					
10 to 100 mm					
IP 55					
Acc. to used valve					
-25 to 55 °C					
5 - 100 % with	n condensation				
	15000 an 10 to 1 IP Acc. to u -25 to				

Wiring diagram of actuator Modact MTN

Execution - terminal board

Position transmitter: resistance 2x100 W or without



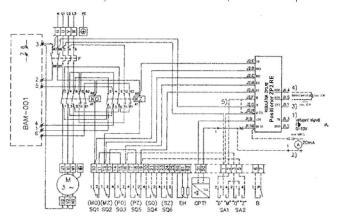


SQ1 (MQ) power switch in "opening" direction.

Position transmitter: capacity CPT 1 1/A 4 - 20 mA

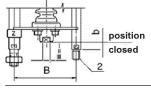
Wiring diagram of actuator Modact MTN Control

With current transmitter, built-in contactor combination, brake BAM and positioner.



3001	VIO)	power switchin opening direction
SQ2(I	MZ)	power switch in "closing" direction
SQ3 (F	20)	limit switch in "opening" direction
SQ5 (F	PZ)	limit switch in "closing" direction
SQ4 (8	SO)	signalisation switch in "opening" direction
SQ6 (8	SZ)	signalisation switch in "closing" direction
EH		heaters 2 x TR 551 10k/A
CPT1		capacity position transmitter
		CPT1/A4 - 20 mA
BAM-0	001	dynamic brake
KO		contactor in "opening" direction
ΚZ		contactor in "closing" direction
F		thermal relay
SA1		control switch "local - remote"
SA2		switch "open - close"
BQ1, E	3Q2	position transmitter 2 x 100 W
ZP2.R	Ε	electronic positioner

Connection dimensions - details of additional specification 52 442



Columns pitch	В	150
Position	b	74
"closed"	g	130
	1	M 20x1,5
Clutch thread	Ш	M 16x1,5
	Ш	M 10x1

Execution	Specific	ation No.	RV 702		
Execution	basic	additional	RV 702		
Bg2II	52 442	XMXX	DN 40÷80		
Bg2III	52 442	XPXX	DN 25		
Bg2l	52 442	XRXX	DN 100÷250		

Specification of actuators Modact MTN and Modact MTN Control

Basic equipment: 2 power switches MO, MZ

2 limit switches PO, PZ

2 limit and signalisation switches SO, SZ

1 position transmitter - resist. 2x100 W or cap. CPT1/A

2 limit switches PO, PZ

2 limit and signalisation switches SO, SZ

Basic	technic:	al data :

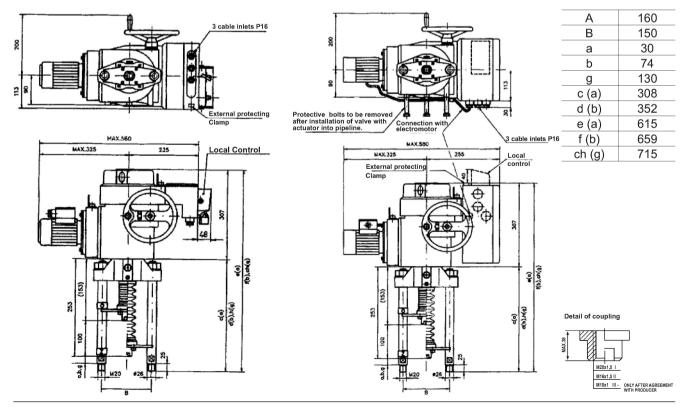
	Power switch	Disc at	Resetting	T1		Electr	omotor		Wei	ight	Specific	ation No.											
Тур	setting range kN	Direct power kN				rpm	In (400V) A	<u>lz</u> In	Aluminium	Cast	Basic	Additional											
			50		180	900	0.67	2.5				XX0X											
		17	80		180	900	0.67	2.5		45		XX1X											
MT 15	5 11,5 - 15		125	10 - 100	250	1380	0.77	3.4	33			XX3X											
			36	120	660	0.67	2.2				XX2X												
			27		120	660	0.67	2.2			52 442	XXAX											
			50		180	900	0.67	2.5			32 442	XX4X											
															80	80	180	900	0.67	2.5			
MT 25	15 -25	32,5	125	10 - 100	250	1380	0.77	3.4	33	45		XX6X											
			36		120	660	0.67	2.2				XX7X											
			27		120	660	0.67	2.2				XX8X											

Execution, electric connection:

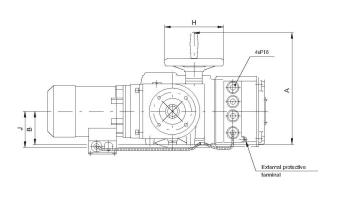
Execution, electric connection.					
Via terminal board				6XXX	
With conector KBSN (for Modact	MTN execu	tion only)		7XXX	
Transmitter for Modact MTN	Capacity to	ransmitter CPT 1/A 4 - 20 mA		XXX0	
Transmitter for Wodact WTN	Resistance	Resistance transmitter 2 x 100 Ω			
Additional electric equipment			With resistance transmitter2 x 100 Ω	With capacity transmitter CPT 1/A	
Made at MTNI avacution	With local	control - terminal board	XXX3	XXX1	
Modact MTN execution	With unloc	k control - conector KBNS	XXX3	XXX1	
	\A/(4)= = -4 [= = = [Without brake BAM and positioner	XXX4	XXXA	
	Without local control	With brake BAM, without positioner	XXX5	XXXB	
Modact MTN Control execution (with built-in contactor	CONTROL	With brake BAM and with positioner		XXXC	
combination)	1400	Without brake BAM and positioner	XXX7	XXXD	
22	With local control	With brake BAM, without positioner	XXX8	XXXE	
	CONTROL	With brake BAM and positioner		XXXF	

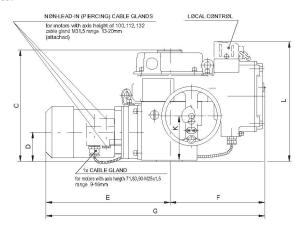
Note: When execution with flasher is requested, please specify this requirement in writing - execution with flasher.

Dimensions of actuator Modact MTN Dimensions of actuator Modact MTN Control



52 030 a 52 031





Type marking	Α	В	С	D	Е	F	G	Н	J	K	L
52 030	305	90	300	78	334	258	592	160	99	120	325
52 031	376	120	328	92	436	258	694	200	-	144	328

Specifikace pohonu Modact MOP

									XX XXX	X	Х	Χ	Χ
Connection	Output of	naft type A	Via termir	nal board						5			
dimensions	Output Si	iait type A	With conr	nector						F			
_ocal control, positi	on indicate	or											
			Without Id	Without local control, without position indicator							1	\Box	
Resistance texecution with			Local con	Local control							4	T	\exists
execution with	iout trailsi	HILLEI	Local con	Local control for actuators Modact MOP Control							7	\dashv	\exists
					tudioro mi						В	\dashv	\dashv
Capacity transmitter CPT 1/A		r	_				-					\dashv	\dashv
CPT	Г 1/А										E	-	4
			Local cor	itrol for ac	tuators Mo	odact MOF	Control				Н	_	_
	Mo	ment	<u>Б</u> -7	a)		Electro	omotor						
Type			nrir ee	Stroke									
marking	Tripping	Driving	Running	St	Power	rpm	I, (400V)	I_z/I_n					
	(Nm)	(Nm)	(1/min.)	(ot)	(kW)	(1/min.)	(A)	(-)					
MØP 40/70 - 7		70	7		0,05	650	0,42	1,6				J	
ИØР 40/65 - 9		65	9		0,06	830	0,34	2,0				0	
MØP 40/55 - 15		55	15		0,09	870	0,47	2,0				1	\Box
MØP 40/75 - 25	20-40	75	25		0,18	1350	0,56	3,0				2	
MØP 40/65 - 40		65	40		0,25	1350	0,76	3,0				3	
MØP 40/50 - 50		50	50		0,25	2830	0,68	4,0	52 030			4	
MØP 40/60 - 80		60	80		0,37	2740	1,00	3,5				5	
ИØР 80/135 - 7		135	7		0,09	630	0,36	2,2				K	
ИØР 80/140 - 9	40-80	140	9		0,12	890	0,60	2,5				6	
MØP 80/135 - 15	40-00	135	15	2-250	0,18	835	0,62	2,3				7	
ИØР 80/105 - 25		105	25		0,25	1350	0,76	3,0				8	\Box
MØP 100/130 - 9		130	9		0,12	890	0,60	2,5				0	Ц
MØP 100/130 - 15		130	15		0,25	850	0,78	2,7				1	
MØP 100/150 - 25		150	25		0,37	920	1,20	3,1				2	
MØP 100/170 - 40	63-100	170	40		0,55	1395	1,45	3,9	52 031		-	3	_
MØP 100/150 - 63		150	63		0,75	1395	1,86	4,0				4	\Box
MØP 100/200 - 80	1	200	80		1,1	2845	2,40	6,1				E	_
MØP 100/150 - 100	-	150	100		1,1	1410	2,65	4,3				5	4
MØP 100/150 - 145		150	145		1,5	2860	3,30	5,5				F	

the table continues on next page

			XX XXX	Х	X :	X :	X X
Signaliza	tion, position transmitter, blin	ker					
	Without signalisation, positi	on transmitter and blinker					0
ors	Position transmitter						1
D at	Signalization switches						2
act ⊀ ∨	Signalization switches and	position transmitter					3
Only for actuators Modact MOP	Blinker					Π.	4
₹ŏ	Position transmitter, blinker						5
o -	Signalization switches and blinker						6
	Signalization switches, posi						7
Signaliza	tion, position transmitter, blin	ker			\perp	\perp	\perp
		Position transmitter				_	Α
	Complete equipment	Signalization switches and position transmitter			\perp	_	В
	Sch P-0781	Position transmitter, blinker			\perp	-	С
0		Signalization switches, position transmitter and blinker			\perp		D
ont		Without signalization, without posit. transmitter and blinker					E
Ŏ		Position transmitter				-	F
Only for actuators Modact MOP Control		Signalization switches			\perp	- (G
Σ	Without positioner	Signalization switches and position transmitter					Н
ac	William positioner	Blinker					1
9		Position transmitter, blinker					J
<u>≥</u> s		Signalization switches, blinker					K
ţo		Signalization switches, position transmitter and blinker					L
tua		Without signalization, without position transm. and blinker					M
ac		Position transmitter					N
for		Signalization switches				,	Ø
کِ	Without positioner	Signalization switches and position transmitter					Р
Ō	and brake BAM	Blinker]	R
		Position transmitter, blinker					S
		Signalization switches, blinker					T
		Signalization switches, position transmitter and blinker				T	U
This mar	k is valid for the the types of t	he actuators					F

-			XX XXX	Х	X	Χ	X.	X
Signaliza	tion, position transmitter, blin	ker						
	Without signalisation, positi	on transmitter and blinker		П			0	
ors	Position transmitter			П			1	
<u>o ta</u>	Signalization switches						2	
act	Signalization switches and	position transmitter					3	
Only for actuators Modact MOP	Blinker			П			4	
å≤	Position transmitter, blinker						5	
o -	Signalization switches and						6	
	Signalization switches, posi	tion transmitter, blinker					7	
Signaliza	tion, position transmitter, blin	ker						
		Position transmitter					Α	
	Complete equipment	Signalization switches and position transmitter					В	
	Complete equipment Sch P-0781	Position transmitter, blinker					С	
0		Signalization switches, position transmitter and blinker					D	
ont		Without signalization, without posit. transmitter and blinker					Е	
Ŏ		Position transmitter					F	
9		Signalization switches				,	G	
Only for actuators Modact MOP Control	Without positioner	Signalization switches and position transmitter					Н	
acl	William positioner	Blinker					I	
<u>6</u>		Position transmitter, blinker					J	
s S		Signalization switches, blinker					K	
tor		Signalization switches, position transmitter and blinker					L	
tua		Without signalization, without position transm. and blinker					M	
ac		Position transmitter					N	
for		Signalization switches				1	Ø	
€	Without positioner	Signalization switches and position transmitter					Р	
Ō	and brake BAM	Blinker					R	
		Position transmitter, blinker					S	
		Signalization switches, blinker					Ţ	
		Signalization switches, position transmitter and blinker					U	
This mar	k is valid for the the types of	he actuators						Ρ



EAG, EAH EAJ, EAK

Electric actuators SAR 07.5, SAR Ex 07.5 SAR 10.1, SAR Ex 10.1 Auma

Technical data

Туре	SAR 07.5	SAR Ex 07.5	SAR 10.1	SAR Ex 10.1				
Marking in valve's specification No.	EAG	EAH	EAJ	EAK				
Voltage	380 or 400 V							
Frequency	50 Hz							
Motor power		See specific	ation table					
Control		3 - position control or	with signal 4 - 20 mA					
Nominal force	20	Nm ~ 10 kN; 25 Nm ~	12,5 kN; 30 Nm ~ 1	5 kN				
Travel	А	cc. to the valve stroke	16, 25, 40, 63, 100 m	ım				
Enclosure		IP	67					
Process medium max. temperature		Acc. to us	ed valve					
Ambient temperature range	-25 až 40°C							
Ambient humidity limit	100 %							
Weight	20 kg							

Specification of Auma actuators

		SA	Х	XX	XX.X
Туре		SA			
Type Duty	Control		R		
Execution	Normal			Ex	
	Non-explosive				
Actuator's size	07.5				07.5
	10.1				10.1

Output drive type A (thread TR 36x6 LH, flange size F10)

			SAR 10.1 SAR Ex 10.1	_	SAR 10.1, SAR Ex 10.1	
(rpm)	4	-		[\	0,09	
	5,6	torque		[kW	0,09	
eed	8	ģ		wer	0,18	
ds	11	jing	60-120	bov	0,18	
Output speed	16	Tripping	Nm	Motor	0,37	
ō	22		Mo	Ψ	0,37	
	32					
	45				0,75	

Output drive type A (thread TR 20x4 LH, flange size F10)

Output speed (rpm)			SAR 07.5 SAR Ex 07.5		SAR 07.5, SAR Ex 7.5
	4	torque		5	0,045
	5,6			power [kW	0,045
	8				0,09
ds 1	11	Tripping	30-60		0,09
tpul	16	ig	Nm	Motor	0,18
0	22			Mo	0,18
	32				0,37
	45				0,37

Accessories

2 TANDEM switches

Gearing for signalisation of position

Mechanical position indicator

Potentiometer 1x200 Ω

Electronic position transmitter RWG (potentiometer included), 4 - 20 mA, 2-wire

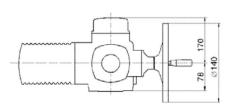
Electronic position transmitter RWG (potentiometer included), 4 - 20 mA, 3/4-wire

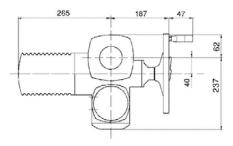
Inductive position transmitter IWG, 4 - 20 mA

AUMATIC - for continuous control (specification of accessories acc. to catalogue of producer)

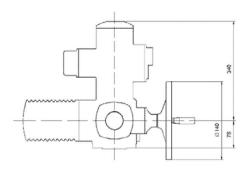
Dimensions of actuators Auma

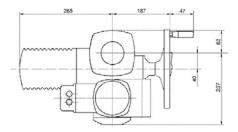
Normal execution



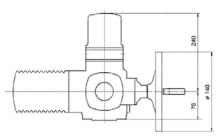


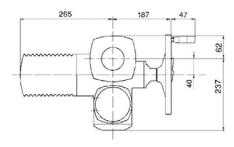
Version with AUMATIC



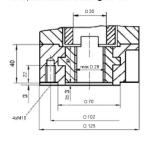


Ex version

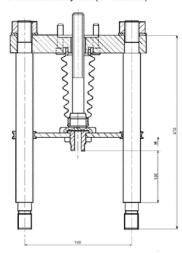




Output shaft A, flange F10



Attachement yoke (4 columns)





Electric actuators ...AB5 Schiebel

Technical data

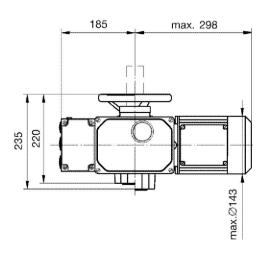
Type	rAB5	exrAB5					
Marking in the valve's specification No.	EZG	EZH					
Voltage	400 / 230 V; 230 V	400 / 230 V					
Frequency	50	50 Hz					
Motor power	See specifi	cation table					
Control	3 - position control or	with signal 4 - 20 mA					
Nominal force	25 Nm ~ 12,5 kN	kN; 30 Nm ~ 15 kN					
Stroke	Acc. to valve's stroke	16, 25, 40, 63, 100 mm					
Enclosure	IP 66	IP 65					
Process medium max. temperature	Acc. to us	ised valve					
Ambient temperature range	-25 to 80°C	-20 to 40°C					
Ambient humidity limit	90 % (tropical version 100 % with condensation)						
Weight	16 - 18 kg 16 kg						

Specification of actuators

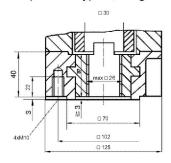
								XX	Χ	AB5	Α	Χ	+ XXX
Execution	on			Non-e	xplosive			ex					
				Norma	Normal								
Duty				Control					r				
Actuator's size									AB5				
Output drive type (threadt TR 20x4 LH,				flange l	flange F10)						Α		
			rAB5		rA	B5	exrAB5						
<u> </u>	exrA	exrAB5	_	400/230V	230V	400/230V							
(rpm)	2,5	<u>o</u>		\geq	0,09	0,09	0,09					2,5	
Output speed (η	5	torque		<u>×</u>	0,12	0,12	0,12					5	
	7,5	으		Motor power [kW	0,09	0,09	0,09					7,5	
ds	10	Tripping	10-30	00	0,12	0,12	0,18					10	
ont	15	ddi	Nm	, p	0,18	0,18	0,18					15	
of t	20	Ľ		Not.	0,18	0,18	0,37					20	
0	30			_	0,37	0,37	0,37					30	
	40				0,37	0,37	0,37					40	
					Potentiometer 1x1000 Ω								F
Δημαροί	oriae			Double potentiometer									FF
Accessories			Electro	Electronic transmitter 4 - 20 mA								ESM2	
				Positio	ner ACTUMA	TIC R							CMR

Dimensions of actuator ... AB5

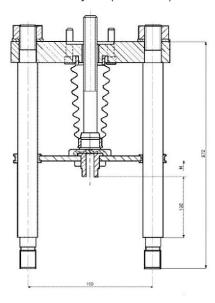
Actuator...AB5



Øutput shaft type A, flange F10



Attachement yoke (4 columns)







Electric actuators ...AB8 Schiebel

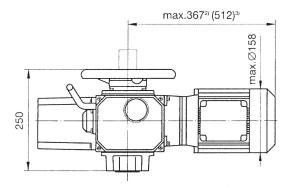
Technical data

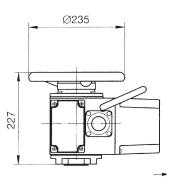
Type	rAB8	exrAB8					
Marking in valve's specification No.	EZK	EZL					
Voltage	400 / 230 V; 230 V	400 / 230 V; 230 V					
Frequency	50 Hz						
Motor power	See specifi	cation table					
Control	3 - position or with signal of 4 - 20 mA						
Nominal force	60 Nm						
Stroke	25	mm					
Enclosure	IP 66	IP 65					
Process medium max. temp.	Acc. to us	sed valve					
Ambient temperature range	-25 to 80°C	-20 to 40°C					
Ambient temperature limit	90 % (tropical version 100 % with condensation)						
Weight	24 kg	20 kg					

Specification of actuator

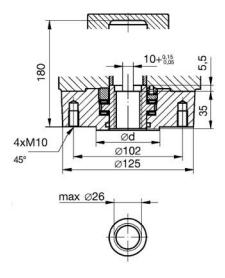
								XX	X	AB8	Α	Χ	+ >	XXX
Executi	on			Non-ex	kplosive			ex						
				Norma	Normal									
Duty				Contro	[r					
Actuato	or size									AB8				
Output	shaft typ	e (conn	ection flange si	ze F10,	thread 36x6)						Α			
		·	*A D 0		rAl	38	exrAB8							
Output speed }rpm]			rAB8		400/230V	230V	400/230V							
	2,5	4)		7	0,12	0,12	0,12					2,5		
	5	Tripping torque		Motor power[kW]	0,12	0,12	0,12					5		
eed	7,5	İ		wer	0,18	0,18	0,18					7,5		
t sp	10	ping	30-80	od.	0,37	0,37	0,18					10		
ndpi	15	Trip	Nm	oto	0,37	0,37	0,37					15		
3	20			ž	0,55	0,75	0,37					20		
	30				0,75 1,10 0,75				30					
	40				1,10 1,10 1		1,10					40		
					Potentiometer 1x1000 Ω								F	
Access	ories				Double potentiometer								FF	
Accessories			Electro	Electronic transmitter 4 - 20 mA								E	SM2	
				Positioner ACTUMATIC R									C	MR

Dimensions of actuators ...AB8

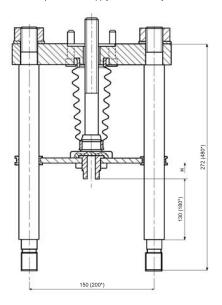




Output shaft type A, flange F10



Attachement yoke (4 columns) * Data in parentheses apply to DN 250 only





Pneumatic actuators Foxboro

Technical data

PO	700	PO 1502						
PF	-G	PFD						
	pmax = 0,6 Mpa	, pmin-see in tab.						
direct	indirect	direct	indirect					
	Pneumatic signal of 20 - 100 kPa							
	Current signal of 0(4) - 20 mA							
	According to table of	, ,						
20, 40,	60 mm	60, 8	0 mm					
	IF	54						
	According t	o used valve						
	-40 t	o 80°C						
	95	5 %						
	See table o	f dimensions						
	direct	direct indirect Pneumatic signs Current signal According to table of 20, 40, 60 mm IF According to -40 to	PFG PF pmax = 0,6 Mpa, pmin-see in tab. direct indirect direct Pneumatic signal of 20 - 100 kPa Current signal of 0(4) - 20 mA According to table of nominal force values					

Accessories

Electropneumatic positioner (analogous)	Device with electric input of 4 to 20 mA and outlet					
type SRI 990	of controllling air into actuator. It is adjusted by switches and					
	potentiometers.					
Electropneumatic positioner (inteligent)	Device with electric input of 4 to 20 mA and outlet of controllling					
type SRD 991	air into actuator. It is adjusted by PC and special software.					
	Comunication HART, Fieldbus Foundation, PRØFIBUS.					
Electropneumatic positioner (digital)	Device with electric input of 4 to 20 mA and outlet					
type SRD 991 - D	of contr. air into actuator. It is adjusted by a local keyboard					
	and diods, possibly on display.					
Pneumatic positioner type SRP 981	Device with pneumatic input of 20 to 100 kPa to control the					
	pneumatic actuators with pneumatic control signal					
Signalisation switches type SGE 985	Adjustable end position switches					
Air set type A 3420	Reduces control air pressure to a value requied					
Electropneumatic positioner type SRI 986	Analog positioner with input signal of 4 (0) - 20 mA					

Operating conditions

Pneumatic actuators FOXBORO can operate with extremely high ambient temperatures with unique resistance to shock loads. They excel with resistance to vibrations and reached 10° of cycles in operation. It is possible to deliver the actuator with both fail to open and fail to close function, possibly with a position blocking (air lock) upon feeding pressure air supply failure. Various accessories can be delivered together with the actuator.

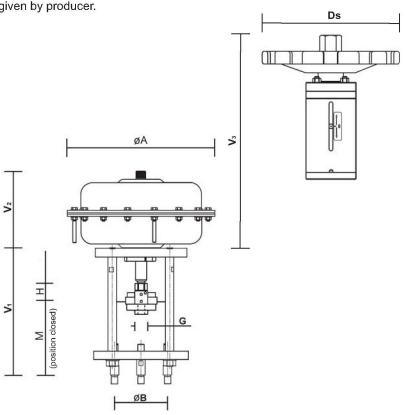
Direct and indirect functions

Direct function ensures that actuator's stem retracts upon control air supply failure (valve opens). Indirect function ensures that actuator's stem extends upon control air supply failure (valve closes).

Dimensions and weights of Foxboro actuators

DN	Actuator	Н	Α	В	G	М	V1	V2	V3	Ds	m [kg]	m (+ HW)
25	PØ 700	16	405	150	M10x1	160	278	227	600	350	65	82
50	PØ 700	25	405	150	M16x1,5	160	278	227	600	350	65	82
100	PØ 1502	40	550	150	M20x1,5	160	324	409			148	
125, 150	PØ 1502	63	550	150	M20x1,5	160	337	409			148	

Note: Face to face dimensions [mm] Missing data to be given by producer.



Valve specification No. of Foxboro actuators

	PX XXX	XΧ	XX	X Z	X >
Actuator type	PA 700				
•	PA 1502				f
Colour	white	В			
Spring range [bar]	2,0 - 3,5		FS		
	1,8 - 2,7		JC		
	1,5 - 3,8		VI		
Hand wheel	without wheel			0	
	heavy wheel			Н	
Function	direct			1	Α
	indirect			7	Z
Stroke [mm]	20				1
	40				E
	60				(
	80				[

DN	Actuator type	Function	Stroke [mm]	Spring range [bar]	Setting of spring [bar]	Feeding pressure min. [bar]
25	PO 700 BJCxZA	Fail to close	20	1,8 - 2,7	1,98 - 2,7	4,8
	PO 700 BJCxAA	Fail to open	20	1,8 - 2,7	1,8 - 2,55	4,5
F0	PO 700 BVIxZB	Fail to close	40	1,5 - 3,8	2,36 - 3,8	5,3
50	PO 700 BVIxAB	Fail to open	40	1,5 - 3,8	1,5 - 2,93	5,3
100	PO 1502 BFSOZC	Fail to close	60	2 - 3,5	2,5 - 3,5	5
100	PO 1502 BFSOAC	Fail to open	60	2 - 3,5	2 - 3	4,5
1/2 120	PO 1502 BFSOZD	Fail to close	80	2 - 3,5	2,3 - 3,5	5
	PO 1502 BFSOAD	Fail to open	80	2 - 3,5	2 - 3,18	5

Maximal permissible overpressures [MPa]

Material	PN					Tem	perature	[°C]				
		100	150	200	250	300	350	400	450	500	550	600
Cast steel	16	1.36	1.27	1.14	1.04	0.94	0.88	0.84				
1.0619	25	2.13	1.98	1.78	1.62	1.47	1.37	1.32				1
	40	3.41	3.17	2.84	2.60	2.35	2.19	2.11				
	63	5.37	4.99	4.48	4.09	3.71	3.45	3.33				
	100	8.53	7.92	7.11	6.50	5.89	5.48	5.28				
	160	13.6	12.7	11.4	10.4	9.40	8.80	8.40				
	250	21.3	19.8	17.8	16.2	14.7	13.7	13.2				
	320	27.2	25.4	22.8	20.8	18.8	17.6	16.8				
	400	34.1	31.7	28.4	26.0	23.5	21.9	21.1				
Alloy steel	16	1.63	1.58	1.49	1.43	1.33	1.23	1.15	1.07	0.89	0.35	
1.7357	25	2.54	2.48	2.33	2.23	2.08	1.93	1.80	1.67	1.39	0.55	
	40	4.07	3.96	3.74	3.57	3.33	3.09	2.89	2.67	2.23	0.88	
	63	6.41	6.24	5.88	5.63	5.24	4.86	4.55	4.20	3.51	1.39	
	100	10.17	9.90	9.34	8.93	8.32	7.71	7.22	6.67	5.57	2.21	
	160	16.3	15.8	14.9	14.3	13.3	12.3	11.5	10.7	8.90	3.50	1-2-1
	250	25.4	24.8	23.3	22.3	20.8	19.3	18.0	16.7	13.9	5.50	
	320	32.6	31.6	29.8	28.6	26.6	24.6	23.0	21.4	17.8	7.00	
	400	40.7	39.6	37.4	35.7	33.3	30.9	28.9	26.7	22.3	8.80	
Stainless steell	16	1.63	1.58	1.54	1.46	1.35	1.27	1.15	1.07	0.89	0.79	0.43
1.4931	25	2.54	2.48	2.41	2.29	2.11	1.98	1.80	1.67	1.39	1.23	0.67
	40	4.07	3.96	3.85	3.66	3.38	3.18	2.89	2.67	2.23	1.97	1.06
	63	6.41	6.24	6.06	5.76	5.33	5.00	4.55	4.20	3.51	3.10	1.68
	100	10.17	9.90	9.63	9.14	8.46	7.94	7.22	6.67	5.57	4.92	2.26
	160	16.3	15.8	15.4	14.6	13.5	12.7	11.5	10.7	8.90	7.90	4.30
	250	25.4	24.8	24.1	22.9	21.1	19.8	18.0	16.7	13.9	12.3	6.70
	320	32.6	31.6	30.8	29.2	27.0	25.4	23.0	21.4	17.8	15.8	8.60
	400	40.7	39.6	38.5	36.6	33.8	31.8	28.9	26.7	22.3	19.7	10.6

Notes: